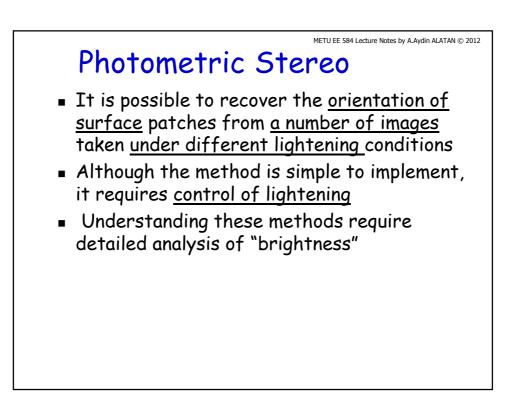
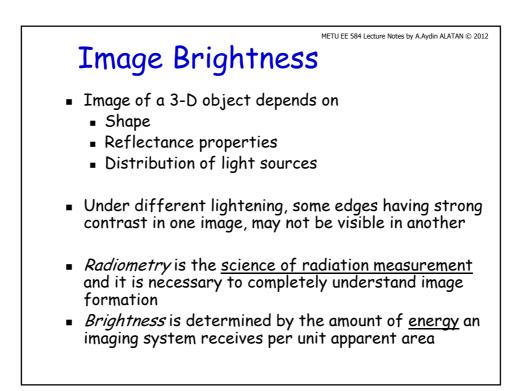
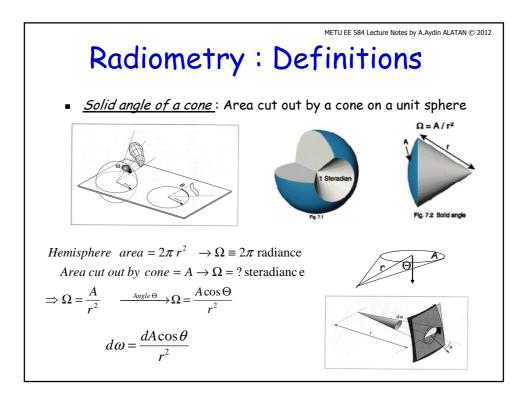
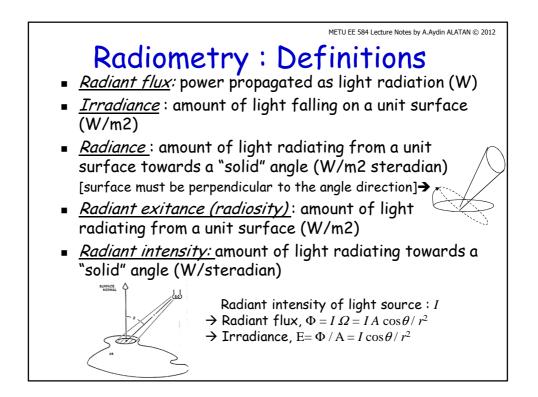
EE 584 MACHINE VISION

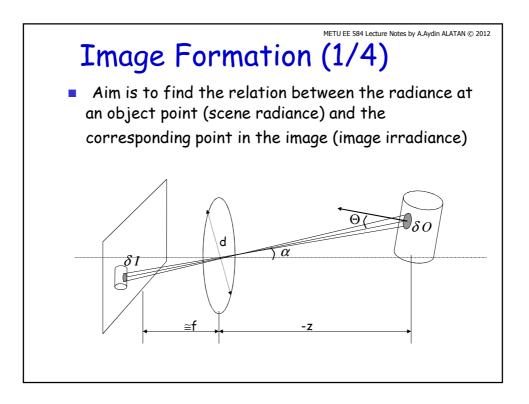
Photometric Stereo Radiometry BRDF Reflectance Map Recovering Surface Orientation

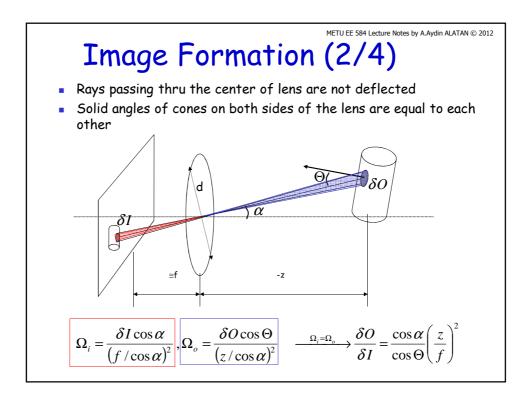


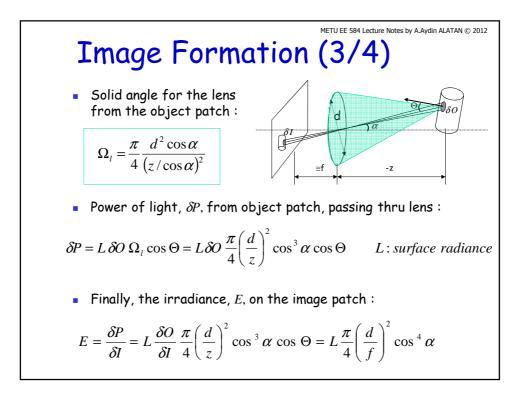


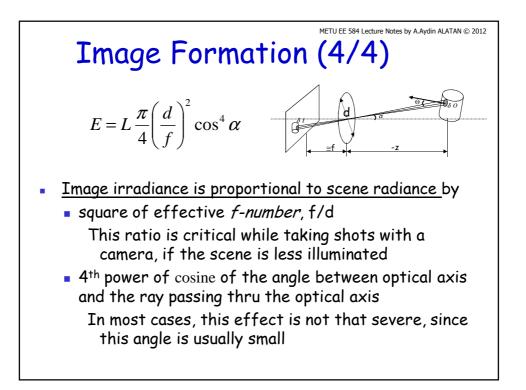


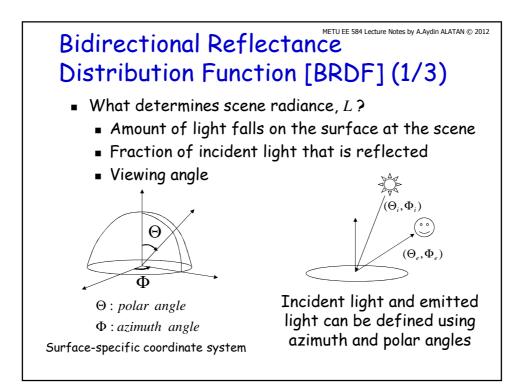


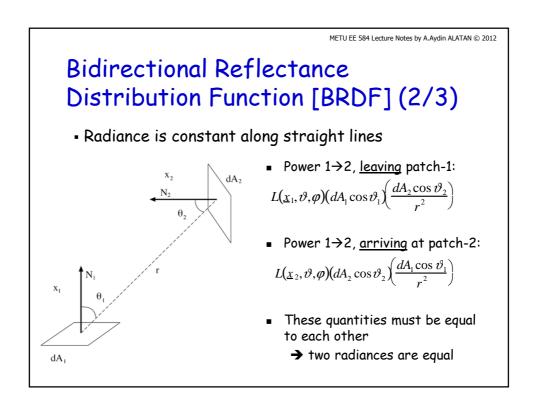


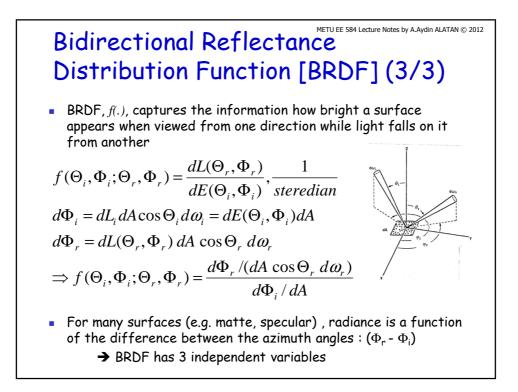


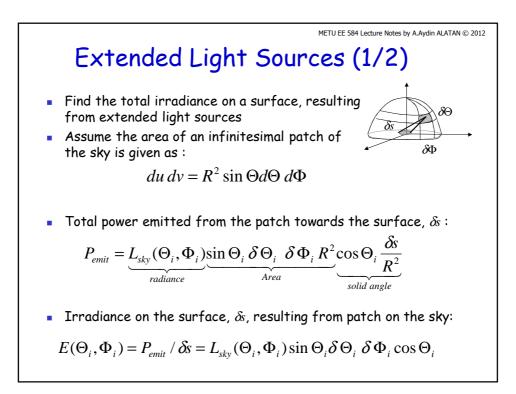


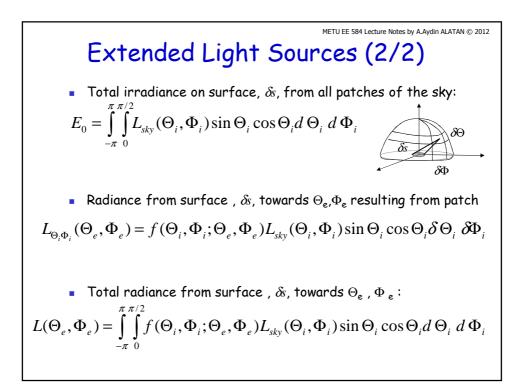


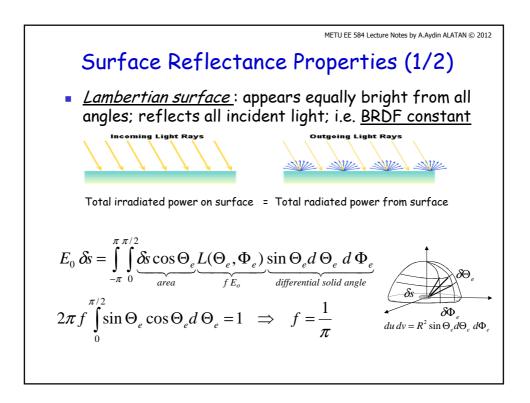


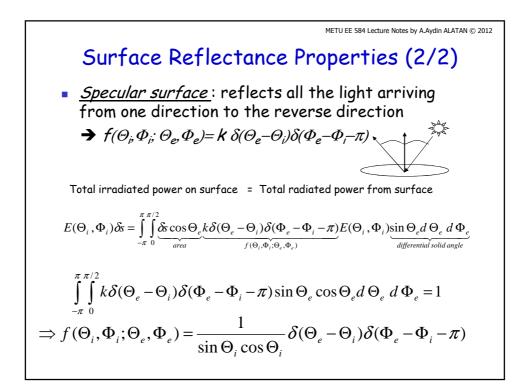


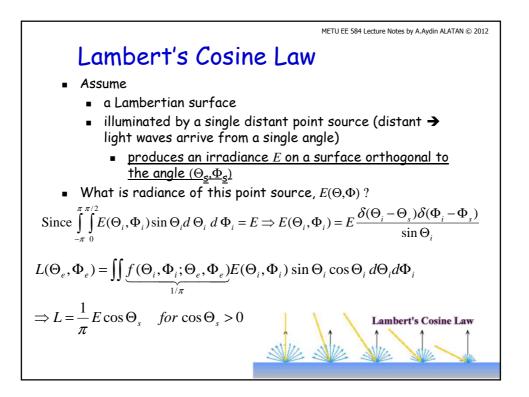


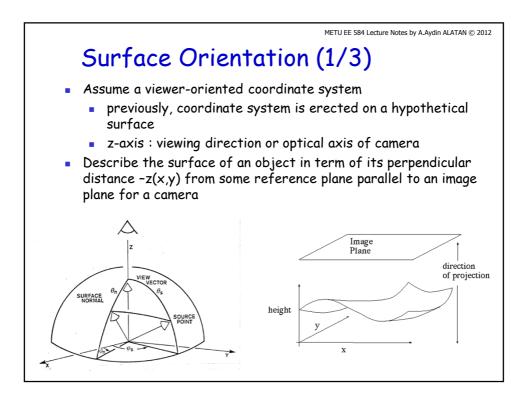


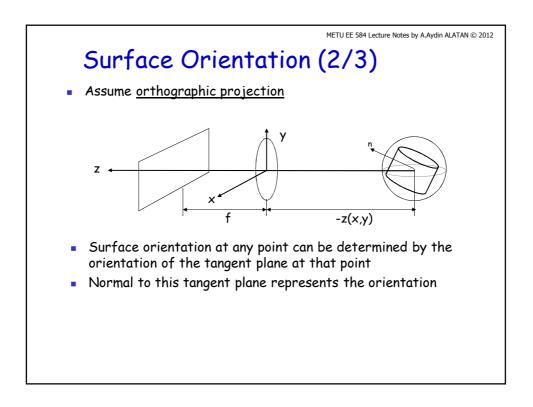


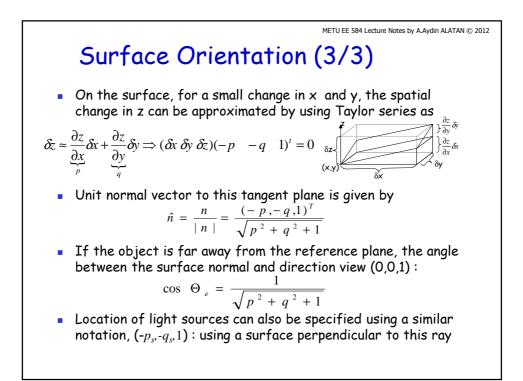












METU EE 584 Lecture Notes by A.Aydin ALATAN © 2012

Reflectance Map (1/2)

- Reflectance Map, R(p,q), should be defined to relate surface orientations (-p,-q,1) to the brightness by taking into account surface reflectance properties and light distributions (-p,-q,1)
- For a source of radiance, *E*, illuminating a Lambertian surface,

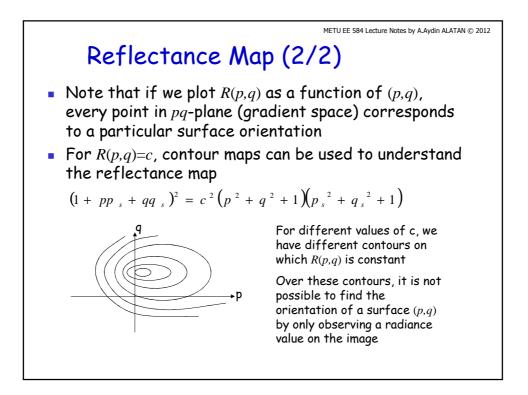
$$L = \frac{1}{\pi} E \cos \Theta_s \quad for \cos \Theta_s > 0$$

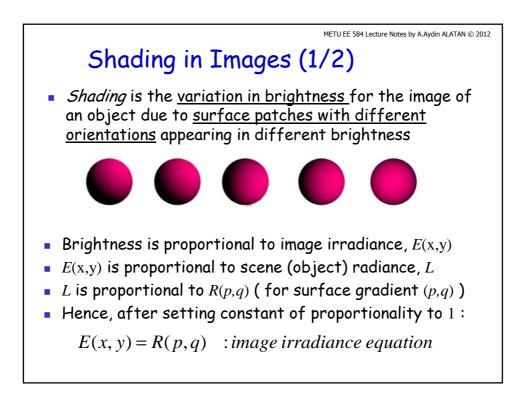
• The angle between illuminating ray and surface normal :

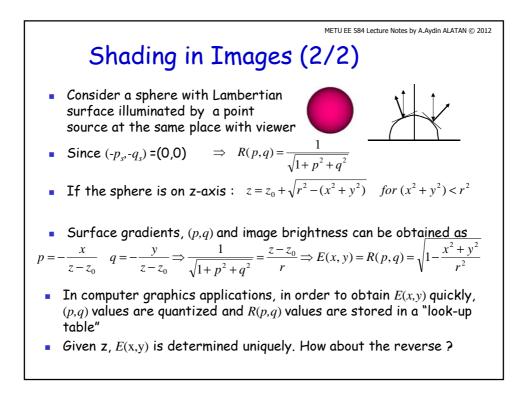
$$\cos \Theta_{s} = \frac{1 + pp_{s} + qq_{s}}{\sqrt{p^{2} + q^{2} + 1}\sqrt{p_{s}^{2} + q_{s}^{2} + 1}}$$

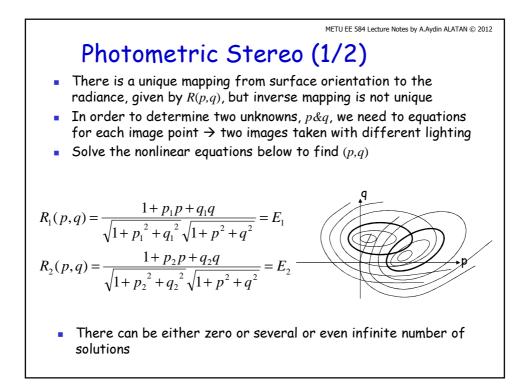
 Since L is proportional to image irradiance, R(p,q) can be defined as above so that it relates surface orientation to brightness

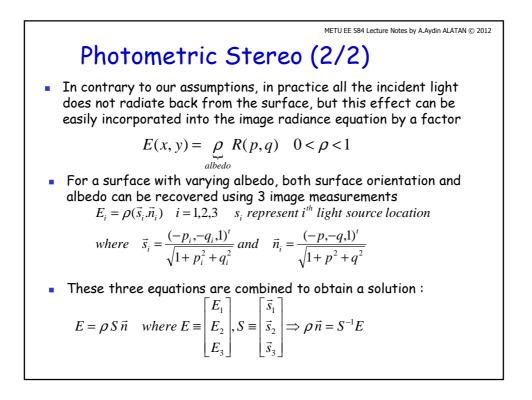
$$R(p,q) = \frac{1+pp_{s}+qq_{s}}{\sqrt{p^{2}+q^{2}+1}\sqrt{p_{s}^{2}+q_{s}^{2}+1}}$$











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